

# GUJARAT TECHNOLOGICAL UNIVERSITY

M.E Semester: 1

Instrumentation and Control Engineering  
(Applied Instrumentation)

Subject Name: PID CONTROLLER

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<b>Sr.No</b>	<b>Course content</b>
1.	<b>Process Models</b> Introduction Static Models Dynamic Models Step Response Methods Methods of Moments Frequency Responses Parameter Estimation Disturbance Models Approximate Models and Unmodeled Dynamics
2.	<b>PID Control</b> Introduction The Feedback Principle PID Control Modifications of the PID Algorithm Integrator Windup Digital Implementation Operational Aspects Commercial Controllers When Can PID Control Be Used?
3.	<b>Controller Design</b> Introduction Specifications Ziegler-Nichols' and Related Methods Loop Shaping Analytical Tuning Methods Optimization Methods Pole Placement Dominant Pole Design Design for Disturbance Rejection
4.	<b>Tuning Methods</b> Introduction A Spectrum of Tools Step-Response Methods

	<p>Frequency-Response Methods  Complete Process Knowledge  Assessment of Performance</p>
5.	<p><b>Automatic Tuning and Adaptation</b>  Introduction  Process Knowledge  Adaptive Techniques  Model-Based Methods  Rule-Based Methods  Commercial Products  Integrated Tuning and Diagnosis</p>
6.	<p><b>Control Paradigms</b>  Introduction  Cascade Control  Feedforward Control  Model Following  Nonlinear Elements  Neural Network Control  Fuzzy Control  Interacting Loops  System Structuring</p>

Reference Books:

1. PID controllers: theory, design, and tuning *by* Karl J. Astrom and Tore Hagglund , Instrument Society of America (ISA)
2. Published Research Papers on PID controller tuning