

GUJARAT TECHNOLOGICAL UNIVERSITY
BRANCH NAME: ELECTRICAL ENGINEERING
SUBJECT NAME: CONTROL SYSTEMS
SUBJECT CODE: 2910901
P.D.D.C. 1st SEMESTER

Type of course:

Prerequisite:

Rationale: Automatic control of industrial processes is essential for increasing the output and in turn the profit of an industry. As a result, most of the companies are using automatic control of the machineries and processes. As an engineer, a student must know the basics of automatic control system. This subject is intended to supplement the basic skill of an engineer.

Teaching and Examination Scheme:

Teaching Scheme			Credits C	Examination Marks				Total Marks
L	T	P		Theory Marks		Practical Marks		
				ESE (E)	PA (M)	ESE (V)	PA (I)	
3	0	0	3	70	30	0	0	100

Content:

Sr. No.	Content	Total Hrs	% Weightage
1	Introduction to control problem Industrial Control examples. Mathematical models of physical systems. Control hardware and their models. Transfer function models of linear time-invariant systems. Feedback Control: Open-Loop and Closed-loop systems. Benefits of Feedback. Block diagram algebra.	05	15
2	Time Response Analysis Standard test signals. Time response of first and second order systems for standard test inputs. Application of initial and final value theorem. Design specifications for second-order systems based on the time-response. Concept of Stability. Routh-Hurwitz Criteria. Relative Stability analysis. Root-Locus technique. Construction of Root-loci.	12	25
3	Frequency-response analysis Relationship between time and frequency response, Polar plots, Bode plots. Nyquist stability criterion. Relative stability using Nyquist criterion – gain and phase margin. Closed-loop frequency response.	08	20
4	Introduction to Controller Design Stability, steady-state accuracy, transient accuracy, disturbance rejection, insensitivity and robustness of control systems. Root-loci method of feedback controller design. Design specifications in frequency-domain. Frequency-domain methods of design. Application of Proportional, Integral and Derivative Controllers, Lead and Lag compensation in designs. Analog and Digital implementation of controllers.	12	25
5	State variable Analysis	06	15

	Concepts of state variables. State space model. Diagonalization of State Matrix. Solution of state equations. Eigen values and Stability Analysis. Concept of controllability and observability. Pole-placement by state feedback. Discrete-time systems. Difference Equations. State-space models of linear discrete-time systems. Stability of linear discrete-time systems.		
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Reference Books:

- M. Gopal, “Control Systems: Principles and Design”, McGraw Hill Education, 1997.
- B. C. Kuo, “Automatic Control System”, Prentice Hall, 1995.
- K. Ogata, “Modern Control Engineering”, Prentice Hall, 1991.
- J. Nagrath and M. Gopal, “Control Systems Engineering”, New Age International, 2009

Course Outcome:

Students will be able to:

- Understand the modelling of linear-time-invariant systems using transfer function and state-space representations.
- Understand the concept of stability and its assessment for linear-time invariant systems.
- Design simple feedback controllers.

Major Equipment:

List of Open Source Software/learning website:

- E-materials available at the website of NPTEL- <http://nptel.ac.in/>